

主要规格 Main Specification

机型 Model	电源容量 (KVA) Power Source	适用成型机 (ton) Recommended I. M. M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (Nl/cycle) Air Consumption	净重 (KG) Net Weight
BRTR13WDS5PC	3.2	360-700T	AC伺服马达 AC Servo motor	四吸两抱	1800	P:800 R:800	1350	10	2.08	7.8	6.8	450

机型表示: W: 双截式 D: 双臂机械手 (成品臂+料头臂) S5: 五轴AC伺服马达驱动 (成品臂/料头臂上下、引拔+横行)
Denote:W:Telescopic type. D:Product arm + runner arm. S5:Five-axis driven by AC Servo Motor.

The diagram consists of two views of the BRTR13WDS5PC robotic arm. The left view is a side profile showing the vertical travel (A), horizontal travel (B), and the distance from the base to the end effector (D, E). The right view is a front elevation showing the horizontal travel (J, L), vertical travel (F, G), and the distance from the base to the end effector (H, I, K, M, N). The dimensions are labeled with letters A through N.

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTR13WDS5PC	1720	2690	1350	435	1800	390	195	245	148	515	800	1520	420	800